

<b>STN</b>	<b>Kozmická technika. Rozhranie a komunikačný protokol pre MIL-STD-1553B dátovú zbernicu na palube kozmických lodí.</b>	<b>STN EN 16603-50-13</b>
		31 0543

Space engineering - Interface and communication protocol for MIL-STD-1553B data bus onboard spacecraft

Táto norma obsahuje anglickú verziu európskej normy.  
This standard includes the English version of the European Standard.

Táto norma bola oznámená vo Vestníku ÚNMS SR č. 01/15

Obsahuje: EN 16603-50-13:2014

**120155**

---

Úrad pre normalizáciu, metrológiu a skúšobníctvo SR, odbor SÚTN, 2015  
Podľa zákona č. 264/1999 Z. z. v znení neskorších predpisov sa môžu slovenské technické normy  
rozmnožovať a rozširovať iba so súhlasom Úradu pre normalizáciu, metrológiu a skúšobníctvo SR.

**EUROPEAN STANDARD**  
**NORME EUROPÉENNE**  
**EUROPÄISCHE NORM**

**EN 16603-50-13**

September 2014

ICS 49.140

English version

**Space engineering - Interface and communication protocol for  
MIL-STD-1553B data bus onboard spacecraft**

Ingénierie spatiale - Interface et protocole de  
communication pour de bus de données embarqué MIL-  
STD 1553B

Raumfahrttechnik - Schnittstellen und  
Kommunikationsprotokoll für MIL-STD-1553B Datenbusse  
in Raumfahrzeugen

This European Standard was approved by CEN on 1 March 2014.

CEN and CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration. Up-to-date lists and bibliographical references concerning such national standards may be obtained on application to the CEN-CENELEC Management Centre or to any CEN and CENELEC member.

This European Standard exists in three official versions (English, French, German). A version in any other language made by translation under the responsibility of a CEN and CENELEC member into its own language and notified to the CEN-CENELEC Management Centre has the same status as the official versions.

CEN and CENELEC members are the national standards bodies and national electrotechnical committees of Austria, Belgium, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Finland, Former Yugoslav Republic of Macedonia, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland, Turkey and United Kingdom.



**CEN-CENELEC Management Centre:  
Avenue Marnix 17, B-1000 Brussels**

## Table of contents

---

<b>Foreword .....</b>	<b>7</b>
<b>1 Scope.....</b>	<b>8</b>
<b>2 Normative references.....</b>	<b>10</b>
<b>3 Terms, definitions and abbreviated terms.....</b>	<b>11</b>
3.1 Terms from other standards.....	11
3.2 Terms and definitions to the present standard .....	11
3.3 Abbreviated terms.....	12
3.4 Conventions.....	13
3.4.1 Bit numbering convention.....	13
3.4.2 Sub-address convention .....	13
<b>4 Overview.....</b>	<b>14</b>
4.1 Context.....	14
4.2 Approach.....	14
4.3 Reference architecture .....	15
4.3.1 Communication devices architecture.....	15
4.3.2 Mapping on CCSDS/SOIS sub-network layer.....	15
4.3.3 Service model .....	17
4.3.4 1553 bus topology.....	18
4.4 1553 bus scheduling aspects.....	19
4.4.1 Bus profiling and scheduling .....	19
4.4.2 Bandwidth pre-allocation .....	21
4.4.3 Implementation of the bus profile .....	23
4.5 Description of services.....	25
4.5.1 Overview.....	25
4.5.2 Time service.....	27
4.5.3 Communication Synchronization service .....	31
4.5.4 Distribution and acquisition: Set and Get Data services .....	34
4.5.5 Data Block Transfer service .....	41
4.5.6 Terminal Management services .....	49

<b>5 Physical Layer requirements .....</b>	<b>50</b>
5.1 Overview .....	50
5.2 General.....	52
5.3 Data bus characteristics.....	52
5.4 Terminal characteristics .....	52
5.5 Connectors .....	53
5.5.1 General.....	53
5.5.2 Pin allocation for 15-pin.....	54
5.5.3 Pin allocation for remote terminal nominal bus .....	54
5.6 Transmission method .....	55
<b>6 Data Link Layer requirements .....</b>	<b>56</b>
6.1 General.....	56
6.2 Data Words and Messages.....	56
6.2.1 Data word format .....	56
6.2.2 Messages .....	58
6.3 Terminal operation.....	59
6.4 Subaddress usage.....	59
6.5 Message retries .....	59
<b>7 Services definition.....</b>	<b>61</b>
7.1 Time service .....	61
7.1.1 TimeData primitive .....	61
7.1.2 TimeSynchronize primitive .....	62
7.2 Communication Synchronization service .....	63
7.2.1 CommunicationSynchronize primitive.....	63
7.3 Set Data service .....	64
7.3.1 SendData primitive.....	64
7.3.2 ReadStatus primitive .....	66
7.4 Get Data service .....	67
7.4.1 ReceiveData primitive .....	67
7.4.2 ReadData primitive .....	69
7.5 Data Block Transfer Service .....	69
7.5.1 SendData primitive .....	69
<b>8 Protocol specification .....</b>	<b>71</b>
8.1 Overview .....	71
8.2 Time service .....	71
8.2.1 Time Data primitive .....	71

8.2.2	Time Synchronize primitive .....	72
8.3	Communication Synchronization service .....	74
8.3.1	Requirements when the Time Synchronization service is implemented.....	74
8.3.2	Requirements when the Time Synchronization service is not Implemented .....	75
8.3.3	BC Requirements for Accurate Message Transfer (optional).....	76
8.4	Set Data service .....	77
8.4.1	BC requirements .....	77
8.4.2	RT Requirements.....	77
8.5	Get Data service .....	77
8.5.1	BC requirements .....	77
8.5.2	RT requirements .....	78
8.6	Data Block Transfer service .....	78
8.6.1	Data Distribution requirements (BC to RT transfer) .....	78
8.6.2	Data Acquisition requirements (RT to BC transfer).....	83
8.7	Terminal Management services .....	89
8.7.1	RT monitoring .....	89
8.7.2	RT Health data word definition .....	90
8.7.3	Terminal configuration commands .....	91
8.7.4	Data wrap around .....	92
<b>9</b>	<b>Test and verification.....</b>	<b>93</b>
9.1	Test specification.....	93
9.2	Tests traceability.....	93
9.3	Test references.....	93
<b>Annex A (informative) Tailoring guidelines.....</b>	<b>94</b>	
A.1	Scope .....	94
A.2	Tailoring options and parameters.....	94
A.2.1	Overview .....	94
A.2.2	Step 1: Function and service selection .....	94
A.2.3	Step 2: Services configuration.....	94
<b>Annex B (informative) Unreferenced requirements in MIL-STD-1553B .....</b>	<b>99</b>	
<b>Bibliography.....</b>	<b>100</b>	

## Figures

Figure 3-1: Bit numbering convention .....	13
Figure 4-1: Architecture of typical communication devices with MIL-STD-1553B I/F.....	16

Figure 4-2: CCSDS/SOIS communication stack architecture.....	16
Figure 4-3: Service model .....	17
Figure 4-4: 1553 Bus topology.....	18
Figure 4-5: Examples of 1553 bus redundancy scheme .....	19
Figure 4-6: Process of Bus Profiling .....	20
Figure 4-7: Example of synchronous access (pre-allocated, populated).....	22
Figure 4-8: Examples of asynchronous access (pre-allocated, unpopulated) .....	22
Figure 4-9: Typical implementation of 1553 messages sequence on BC.....	23
Figure 4-10: Typical communication frame decomposition on BC .....	24
Figure 4-11: Services dependencies .....	26
Figure 4-12: Time Service steps.....	28
Figure 4-13: Time Service .....	29
Figure 4-14: Time distribution and synchronization.....	30
Figure 4-15: Communication Synchronization scenarios .....	31
Figure 4-16: Communication Synchronization .....	32
Figure 4-17: Communication Frame duration adjustment methods.....	33
Figure 4-18: Set Data service .....	36
Figure 4-19: Get Data service.....	39
Figure 4-20: Data Distribution Transfer, BC to RT .....	45
Figure 4-21: Data Distribution timing with Best Effort QoS.....	45
Figure 4-22: Data Distribution timing with Verified Length QoS .....	46
Figure 4-23: Data Acquisition Transfer, RT to BC .....	47
Figure 4-24: Data Acquisition timing with Best Effort QoS .....	48
Figure 4-25: Data Acquisition timing with Verified Length QoS .....	48
Figure 5-1: Bus connectors for separated BCs or RTs .....	50
Figure 5-2: Bus connectors for integrated BCs or RTs .....	51
Figure 5-3: Bus connectors for separated BCs or RTs connected to dual buses .....	51

## **Tables**

Table 5-1: Pin allocation for 15-pin Bus Controller 1553 Bus Connector.....	53
Table 5-2: Pin allocation for 15-pin Remote Terminal 1553 Bus Connector .....	53
Table 5-3: Pin allocation for 9-pin Bus Controller or Remote Terminal 1553 Bus Connector .....	54
Table 5-4: Pin allocation for Remote Terminal nominal bus .....	55
Table 6-1: Subaddress allocation .....	60
Table 7-1: TimeData primitive definition .....	61
Table 7-2: TimeSynchronize primitive definition.....	62
Table 7-3: CommunicationSynchronize primitive definition.....	63

Table 7-4: SendData primitive definition with predefined transfers (Type I) .....	64
Table 7-5: SendData primitive definition with pre-allocated bandwidth (Type II) .....	65
Table 7-6: ReadStatus primitive definition .....	66
Table 7-7: ReceiveData primitive definition with predefined transfers (Type I).....	67
Table 7-8: ReceiveData primitive definition with pre-allocated bandwidth (Type II).....	68
Table 7-9: ReadData primitive definition .....	69
Table 7-10: SendData primitive definition for the Data Block Transfer Service .....	70
Table 8-1: Time Message data words, CCSDS CUC format.....	72
Table 8-2: Communication Frame Synchronization Message Data Word .....	75
Table 8-3: Layout of the Distribution Transfer Descriptor (BC to RT, SA 27R).....	78
Table 8-4: Layout of the Distribution Transfer Confirmation (BC to RT, SA 27T) .....	82
Table 8-5: Layout of the Acquisition Transfer Confirmation, ATC (BC to RT, SA 28R) .....	85
Table 8-6: Layout of the Acquisition Transfer Request, ATR (RT to BC, SA 28T).....	86
Table 8-7: SA 1T: RT_Health & Monitoring data definition.....	90
Table 8-8: RT_Health data definition .....	91
Table 8-9: SA 1R: Terminal Configuration definition .....	92
Table 8-10: Reset Services command definition.....	92
Table A-1 : Requirements selection.....	95
Table A-2 : Services configuration.....	96

## **Foreword**

---

This document (EN 16603-50-13:2014) has been prepared by Technical Committee CEN/CLC/TC 5 "Space", the secretariat of which is held by DIN.

This standard (EN 16603-50-13:2014) originates from ECSS-E-ST-50-13C.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by March 2015, and conflicting national standards shall be withdrawn at the latest by March 2015.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN [and/or CENELEC] shall not be held responsible for identifying any or all such patent rights.

This document has been prepared under a mandate given to CEN by the European Commission and the European Free Trade Association.

This document has been developed to cover specifically space systems and has therefore precedence over any EN covering the same scope but with a wider domain of applicability (e.g. : aerospace).

According to the CEN-CENELEC Internal Regulations, the national standards organizations of the following countries are bound to implement this European Standard: Austria, Belgium, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Finland, Former Yugoslav Republic of Macedonia, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland, Turkey and the United Kingdom.

**1****Scope**

Using standard communication protocols for spacecraft communication links can provide interface compatibility between communication devices and components. Thus, it can improve the design and development process as well as integration and test activities at all levels, and provide the potential of reusability across projects.

The aim of this space engineering standard is to define the interface services and to specify their corresponding bus protocol elements for spacecraft using the MIL-STD-1553B data bus. It also aims at defining requirements for harmonisation of physical interface and usage of the MIL-STD-1553B data link layer features.

Another goal of this standard is to facilitate the bus profiling task by proposing a message scheduling scheme to the mission system architects. Such framework helps to homogenise the allocation and control of communication resources across a single project or spacecraft mission.

The scope of this standard is as follows:

- It details the usage of the MIL-STD-1553B.
- It covers the communication protocols, services and functions needed for exchange of information over MIL-STD-1553B data bus.
- It is limited to necessary and sufficient requirements to ensure compatibility for communication through MIL-STD-1553B data bus for communication devices onboard a spacecraft and across projects.
- It covers a wide spectrum of mission needs.
- It does not modify requirements that are under the scope of MIL-STD-1553B.
- It covers recommendation for verification and test of communication devices communicating through a MIL-STD-1553 data bus.

This Standard provides a comprehensive set of requirements for all communication devices and components onboard a spacecraft, which are connected to a single (redundant) data bus according to MIL-STD-1553B.

Although the standard focuses on the specification of single-bus architecture, questions related to multiple-bus-architectures or the use of repeaters for separable busses (for launchers) are also addressed.

This Standard aims at specifying requirements that are technically feasible, correct, consistent and compliant with the needs and overall technological approach and industrial policies of the participating Agencies and Industry.

This standard may be tailored for the specific characteristic and constraints of a space project in conformance with ECSS-S-ST-00.

**2****Normative references**

The following normative documents contain provisions which, through reference in this text, constitute provisions of this ECSS Standard. For dated references, subsequent amendments to, or revision of any of these publications do not apply. However, parties to agreements based on this ECSS Standard are encouraged to investigate the possibility of applying the more recent editions of the normative documents indicated below. For undated references, the latest edition of the publication referred to applies.

<b>EN reference</b>	<b>Reference in text</b>	<b>Title</b>
EN 16601-00-01	ECSS-S-ST-00-01	ECSS System - Glossary of terms.
	MIL-STD-1553B	Interface Standard for Digital Time Division Command/Response Multiplex Data Bus, Notice 2, 8 <sup>th</sup> September 1986 Notice 3, 31 <sup>st</sup> January 1993 Notice 4, 15 <sup>th</sup> January 1996
	MIL-HDBK-1553A	Military handbook. Multiplex applications handbook, 1 <sup>st</sup> November 1988

**NOTE** The technical requirements and their numbering are identical in Notices 2, 3 and 4 of the MIL-STD-1553B standard. Therefore, ECSS-E-ST-50-13 can be used in complement to any of those MIL-STD-1553B standard notices.

**koniec náhľadu – text d'alej pokračuje v platenej verzii STN**