STN	Inteligentné dopravné systémy (IDS) Kooperatívne IDS Použitie komunikácie V2I a I2V na aplikácie súvisiace so svetelnými križovatkami (ISO/TS 19091: 2017)	STN P CEN ISO/TS 19091
		01 8665

Intelligent transport systems - Cooperative ITS - Using V2I and I2V communications for applications related to signalized intersections (ISO/TS 19091:2017)

Táto norma obsahuje anglickú verziu európskej normy. This standard includes the English version of the European Standard.

Táto norma bola oznámená vo Vestníku ÚNMS SR č. 08/17

Táto predbežná STN je určená na overenie. Pripomienky zasielajte ÚNMS SR najneskôr do 31. 3. 2019.

Obsahuje: CEN ISO/TS 19091:2017, ISO/TS 19091:2017

125101

Úrad pre normalizáciu, metrológiu a skúšobníctvo Slovenskej republiky, 2017

Podľa zákona č. 264/1999 Z. z. o technických požiadavkách na výrobky a o posudzovaní zhody a o zmene a doplnení niektorých zákonov v znení neskorších predpisov sa slovenská technická norma a časti slovenskej technickej normy môžu rozmnožovať alebo rozširovať len so súhlasom slovenského národného normalizačného orgánu.

TECHNICAL SPECIFICATION SPÉCIFICATION TECHNIQUE TECHNISCHE SPEZIFIKATION

CEN ISO/TS 19091

March 2017

ICS 03.220.20; 35.240.60

English Version

Intelligent transport systems - Cooperative ITS - Using V2I and I2V communications for applications related to signalized intersections (ISO/TS 19091:2017)

Systèmes intelligents de transport - Coopérative ITS -Utilisation de communications V2I et I2V pour des applications relatives aux intersections signalées (ISO/TS 19091:2017) Intelligente Transportsysteme - Kooperative ITS -Nutzung von V2I und I2V-Kommunikation für Anwendungen bezogen auf Signalanlagen an Kreuzungen (ISO/TS 19091:2017)

This Technical Specification (CEN/TS) was approved by CEN on 3 March 2017 for provisional application.

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Ref. No. CEN ISO/TS 19091:2017 E

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European foreword

This document (CEN ISO/TS 19091:2017) has been prepared by Technical Committee ISO/TC 204 "Intelligent transport systems" in collaboration with Technical Committee CEN/TC 278 "Intelligent transport systems" the secretariat of which is held by NEN.

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The text of ISO/TS 19091:2017 has been approved by CEN as CEN ISO/TS 19091:2017 without any modification.

STN P CEN ISO/TS 19091: 2017 TECHNICAL SPECIFICATION

ISO/TS 19091

First edition 2017-03

Intelligent transport systems — Cooperative ITS — Using V2I and I2V communications for applications related to signalized intersections

Systèmes intelligents de transport — Coopérative ITS — Utilisation de communications V2I et I2V pour des applications relatives aux intersections signalées



Reference number ISO/TS 19091:2017(E)



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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

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For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: <u>www.iso.org/iso/foreword.html</u>.

The committee responsible for this document is ISO/TC 204, Intelligent transport systems.

Introduction

Cooperative-ITS (C-ITS) is a promising and remarkable advancement of intelligent transport systems (ITS). Numerous cooperative applications are specified that open up new possibilities to make traffic safer, more efficient, and smarter. Technologies are developed and improved to realize and support those new services and applications. To enable those applications, information needs to be reliably communicated between the stationary infrastructure and mobile vehicles.

This document describes the use cases for several applications that address safety, mobility, and ecological sustainability. Each use case has information needs that communication between vehicles and the infrastructure facilitate. It then identifies the information needs for the applications and the requirements to satisfy them. In turn, it maps the requirements into data frames and data elements to fulfil the requirements within the specified message set.

ISO 22951 has a relationship to this document. PRESTO addresses its user needs through the implementation of a specific system architecture similar to that described in NTCIP 1211. This architecture includes traffic signals, message signs, routing systems, human machine interfaces, and fixed detection locations. Many of PRESTO's data value details are "left undefined to allow for discretional definition by each country." The PRESTO architecture detects priority requesting vehicles by installing specific detection equipment at these locations.

This document uses a similar set of user needs to develop the message set between vehicles and the roadside equipment they interface. This document does not address the system architecture other than data needed to fulfil the user needs that will be managed elsewhere in the architecture. It details data values and structures in order to define the interface between these two devices. Routing information is supported in the architecture through other mechanisms and is not a need supported by the vehicle to roadside equipment information flows. The user needs also provide for priority by approach, a preconfigured strategy, and ingress/egress lane requests. This document is based on vehicles periodically broadcasting their location and trajectory information to other vehicle location and request information directly from connected vehicles rather than the detection of the vehicles from other fixed sensing equipment. It does not address the architecture data flows and operations that are detailed within ISO 22951. In other terms, this document provides a connected vehicle alternative for request and status communication without impacting the back office or local intersection operations of priority management.

Intelligent transport systems — Cooperative ITS — Using V2I and I2V communications for applications related to signalized intersections

1 Scope

This document defines the message, data structures, and data elements to support exchanges between the roadside equipment and vehicles to address applications to improve safety, mobility and environmental efficiency. In order to verify that the defined messages will satisfy these applications, a systems engineering process has been employed that traces use cases to requirements and requirements to messages and data concepts.

This document consists of a single document that contains the base specification and a series of annexes. The base specification lists the derived information requirements (labelled informative) and references to other standards for message definitions where available. <u>Annex A</u> contains descriptions of the use cases addressed by this document. <u>Annex B</u> and <u>Annex C</u> contain traceability matrices that relate use cases to requirements and requirements to the message definitions (i.e. data frames and data elements). The next annexes list the base message requirements and application-oriented specific requirements (requirements traceability matrix) that map to the message and data concepts to be implemented. As such, an implementation consists of the base plus an additional group of extensions within this document.

Details on information requirements, for other than SPaT, MAP, SSM, and SRM messages are provided in other International Standards. The focus of this document is to specify the details of the SPaT, MAP, SSM, and SRM supporting the use cases defined in this document. Adoption of these messages varies by region and their adoption may occur over a significant time period.

This document covers the interface between roadside equipment and vehicles. Applications, their internal algorithms, and the logical distribution of application functionality over any specific system architecture are outside the scope of this document.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 22951, Data dictionary and message sets for preemption and prioritization signal systems for emergency and public transport vehicles (PRESTO)

ISO 26684, Intelligent transport systems (ITS) — Cooperative intersection signal information and violation warning systems (CIWS) — Performance requirements and test procedures

SAE J2735TM:2016, Dedicated Short Range Communications (DSRC) Message Set Dictionary

EN 302 637-2 V1.3.2, Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications; Part 2: Specification of Cooperative Awareness Basic Service

ARIB STD-T109, 700 MHz Band Intelligent Transport Systems

ITS FORUM RC-010, 700 MHz Band Intelligent Transport Systems — Extended Functions Guideline, published on March 15, 2012

ETSI/TS 102 894-2 V1.2.2, Intelligent Transport Systems (ITS); Users and applications requirements; Part 2: Applications and facilities layer; common data dictionary

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