

STN	<p>Zariadenia krátkeho dosahu (SRD) Harmonizovaná norma pre prístup k rádiovému spektru Systémy indukčných smyčiek pre robotické sekačky pracujúce vo frekvenčnom rozsahu 100 Hz až 148,5 kHz</p>	<p>STN EN 303 447 V1.3.1</p>
		87 3447

Short Range Devices (SRD); Harmonised Standard for access to radio spectrum; Inductive loop systems for robotic mowers operating within the frequency range 100 Hz to 148,5 kHz

Táto norma obsahuje anglickú verziu európskej normy.
This standard includes the English version of the European Standard.

Táto norma bola oznámená vo Vestníku ÚNMS SR č. 12/22

Obsahuje: EN 303 447 V1.3.1:2022

135773



ETSI EN 303 447 V1.3.1 (2022-07)



**Short Range Devices (SRD);
Harmonised Standard for access to radio spectrum;
Inductive loop systems for robotic mowers operating
within the frequency range 100 Hz to 148,5 kHz**

Reference
REN/ERM-TG28-552

Keywords
harmonised standard, inductive, measurement,
radio

ETSI
650 Route des Lucioles
F-06921 Sophia Antipolis Cedex - FRANCE

Tel.: +33 4 92 94 42 00 Fax: +33 4 93 65 47 16

Siret N° 348 623 562 00017 - APE 7112B
Association à but non lucratif enregistrée à la
Sous-Préfecture de Grasse (06) N° w061004871

Important notice

The present document can be downloaded from:
<http://www.etsi.org/standards-search>

The present document may be made available in electronic versions and/or in print. The content of any electronic and/or print versions of the present document shall not be modified without the prior written authorization of ETSI. In case of any existing or perceived difference in contents between such versions and/or in print, the prevailing version of an ETSI deliverable is the one made publicly available in PDF format at www.etsi.org/deliver.

Users of the present document should be aware that the document may be subject to revision or change of status.

Information on the current status of this and other ETSI documents is available at
<https://portal.etsi.org/TB/ETSIDeliverableStatus.aspx>

If you find errors in the present document, please send your comment to one of the following services:
<https://portal.etsi.org/People/CommitteeSupportStaff.aspx>

If you find a security vulnerability in the present document, please report it through our
Coordinated Vulnerability Disclosure Program:
<https://www.etsi.org/standards/coordinated-vulnerability-disclosure>

Notice of disclaimer & limitation of liability

The information provided in the present deliverable is directed solely to professionals who have the appropriate degree of experience to understand and interpret its content in accordance with generally accepted engineering or other professional standard and applicable regulations.

No recommendation as to products and services or vendors is made or should be implied.
In no event shall ETSI be held liable for loss of profits or any other incidental or consequential damages.

Any software contained in this deliverable is provided "AS IS" with no warranties, express or implied, including but not limited to, the warranties of merchantability, fitness for a particular purpose and non-infringement of intellectual property rights and ETSI shall not be held liable in any event for any damages whatsoever (including, without limitation, damages for loss of profits, business interruption, loss of information, or any other pecuniary loss) arising out of or related to the use of or inability to use the software.

Copyright Notification

No part may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying and microfilm except as authorized by written permission of ETSI.

The content of the PDF version shall not be modified without the written authorization of ETSI.
The copyright and the foregoing restriction extend to reproduction in all media.

© ETSI 2022.
All rights reserved.

Contents

Intellectual Property Rights	5
Foreword.....	5
Modal verbs terminology.....	6
Introduction	6
1 Scope	7
2 References	7
2.1 Normative references	7
2.2 Informative references.....	8
3 Definition of terms, symbols and abbreviations.....	9
3.1 Terms.....	9
3.2 Symbols.....	11
3.3 Abbreviations	11
4 Technical requirements specifications	11
4.1 Environmental profile.....	11
4.2 General	11
4.2.1 Wanted technical performance criteria	11
4.2.2 RMI modes	12
4.2.2.1 General.....	12
4.2.2.2 Operational Modes.....	12
4.2.2.3 Safe Mode	12
4.2.3 Presentation of equipment for testing purposes	12
4.3 Transmitter conformance requirements.....	13
4.3.1 Operating Frequency Range (OFR).....	13
4.3.1.1 Applicability.....	13
4.3.1.2 Description	13
4.3.1.3 Limits	13
4.3.1.4 Conformance.....	13
4.3.2 Transmitter H-field requirements	14
4.3.2.1 Applicability.....	14
4.3.2.2 Description	14
4.3.2.3 Limits	14
4.3.2.4 Conformance.....	14
4.3.3 Transmitter spurious emissions.....	14
4.3.3.1 Applicability.....	14
4.3.3.2 Description	14
4.3.3.3 Limits	15
4.3.3.4 Conformance.....	16
4.3.4 Transmitter Out Of Band (OOB) emissions	16
4.3.4.1 Applicability.....	16
4.3.4.2 Description	16
4.3.4.3 Limits	16
4.3.4.4 Conformance.....	16
4.4 Receiver conformance requirements	16
4.4.1 Introduction.....	16
4.4.2 Receiver Spurious Emissions.....	16
4.4.2.1 Applicability.....	16
4.4.2.2 Description	17
4.4.2.3 Limits	17
4.4.2.4 Conformance.....	17
4.4.3 Receiver Baseline Sensitivity	17
4.4.3.1 Applicability.....	17
4.4.3.2 Description	17
4.4.3.3 Limits	17
4.4.3.4 Conformance.....	17

4.4.4	Receiver Baseline Resilience	17
4.4.4.1	Applicability	17
4.4.4.2	Description	17
4.4.4.3	Limits	18
4.4.4.4	Conformance	18
5	Testing for compliance with technical requirements	18
5.1	Environmental conditions for testing	18
5.2	General conditions for testing	18
5.3	Artificial antenna	18
5.4	Measuring receiver	19
5	Conformance methods of measurement for transmitters and receivers	19
6.1	General	19
6.2	Transmitter conformance methods	20
6.2.1	OFR	20
6.2.2	H-field	21
6.2.3	Transmitter unwanted emissions (spurious and OOB emissions)	21
6.3	Receiver conformance methods	22
6.3.1	Receiver spurious emissions	22
6.3.2	Receiver Baseline Sensitivity	23
6.3.2.1	General	23
6.3.2.2	Receiver-Baseline Sensitivity Test	24
6.3.3	Receiver Baseline Resilience (RBR)	24
6.3.3.1	General	24
6.3.3.2	RBR Test 1: to test that the robotic mower can handle a lost signal	25
6.3.3.3	RBR Test 2: to test that the robotic mower can handle a passage of the boundary wire	26
Annex A (informative):	Relationship between the present document and the essential requirements of Directive 2014/53/EU	28
Annex B (normative):	Test sites and procedures	30
B.1	Boundary and dependent guidance loops	30
B.1.1	Artificial antenna for conducted measurements below 30 MHz	30
B.1.2	General setup and measurement procedure for the current measurement with artificial antenna	32
B.1.3	Differential mode measurement	33
B.1.4	Common mode measurement	34
B.1.5	The reference test garden	34
B.1.6	Test setup for verification artificial antenna	34
B.1.6.1	General	34
B.1.6.2	For Differential Mode Impedance verification	35
B.1.6.3	For Common Mode Impedance verification	35
B.2	Radiated measurements using anechoic chamber or open area test site	36
B.2.1	General	36
B.2.2	Radiated emission measurements < 30 MHz	36
B.2.3	Radiated emission measurements 30 MHz to 1 000 MHz	37
Annex C (informative):	Justification for missing RX-requirements from ETSI EG 203 336	38
C.1	Justification for other RX-requirements	38
Annex D (informative):	TX spurious emission limit assessment below 9 kHz	40
Annex E (informative):	Change history	41
	History	42

Intellectual Property Rights

Essential patents

IPRs essential or potentially essential to normative deliverables may have been declared to ETSI. The declarations pertaining to these essential IPRs, if any, are publicly available for **ETSI members and non-members**, and can be found in ETSI SR 000 314: *"Intellectual Property Rights (IPRs); Essential, or potentially Essential, IPRs notified to ETSI in respect of ETSI standards"*, which is available from the ETSI Secretariat. Latest updates are available on the ETSI Web server (<https://ipr.etsi.org/>).

Pursuant to the ETSI Directives including the ETSI IPR Policy, no investigation regarding the essentiality of IPRs, including IPR searches, has been carried out by ETSI. No guarantee can be given as to the existence of other IPRs not referenced in ETSI SR 000 314 (or the updates on the ETSI Web server) which are, or may be, or may become, essential to the present document.

Trademarks

The present document may include trademarks and/or tradenames which are asserted and/or registered by their owners. ETSI claims no ownership of these except for any which are indicated as being the property of ETSI, and conveys no right to use or reproduce any trademark and/or tradename. Mention of those trademarks in the present document does not constitute an endorsement by ETSI of products, services or organizations associated with those trademarks.

DECT™, PLUGTESTS™, UMTS™ and the ETSI logo are trademarks of ETSI registered for the benefit of its Members. **3GPP™** and **LTE™** are trademarks of ETSI registered for the benefit of its Members and of the 3GPP Organizational Partners. **oneM2M™** logo is a trademark of ETSI registered for the benefit of its Members and of the oneM2M Partners. **GSM®** and the **GSM** logo are trademarks registered and owned by the GSM Association.

Foreword

This Harmonised European Standard (EN) has been produced by ETSI Technical Committee Electromagnetic compatibility and Radio spectrum Matters (ERM).

The present document has been prepared under the Commission's standardisation request C(2015) 5376 final [i.6] to provide one voluntary means of conforming to the essential requirements of Directive 2014/53/EU on the harmonisation of the laws of the Member States relating to the making available on the market of radio equipment and repealing Directive 1999/5/EC [i.3].

Once the present document is cited in the Official Journal of the European Union under that Directive, compliance with the normative clauses of the present document given in table A.1 confers, within the limits of the scope of the present document, a presumption of conformity with the corresponding essential requirements of that Directive and associated EFTA regulations.

National transposition dates	
Date of adoption of this EN:	27 June 2022
Date of latest announcement of this EN (doa):	30 September 2022
Date of latest publication of new National Standard or endorsement of this EN (dop/e):	31 March 2023
Date of withdrawal of any conflicting National Standard (dow):	31 March 2024

Modal verbs terminology

In the present document "**shall**", "**shall not**", "**should**", "**should not**", "**may**", "**need not**", "**will**", "**will not**", "**can**" and "**cannot**" are to be interpreted as described in clause 3.2 of the [ETSI Drafting Rules](#) (Verbal forms for the expression of provisions).

"**must**" and "**must not**" are **NOT** allowed in ETSI deliverables except when used in direct citation.

Introduction

The present document covers Robotic Mowers with Inductive loop systems (RMI) using the frequency range below 148,5 kHz. An RMI system includes:

- RMI docking station: charging stations for the robotic mower and the signal generator/antenna connecting point for the signals on the integral antenna and boundary wire.
- Robotic Mower: receiving part inside the RMI.
- Boundary Wire: user installed antenna.

The present document is structured as follows:

- Clauses 1, 2 and 3 provide a general description on the types of equipment covered by the present document and the definition of terms, symbols and abbreviations used.
- Clause 4 provides the technical requirements specifications, limits and conformance relative to transmitter and receiver.
- Clause 5 specifies the conditions and information for testing of the equipment and interpretation of the measurement results.
- Clause 6 specifies the required measurement methods.
- Annex A (informative) provides the relationship between the present document and the essential requirements of Directive 2014/53/EU [i.3].
- Annex B (normative) provides necessary information on used test sites and procedures.
- Annex C (informative) provides the justification for missing RX-requirements from ETSI EG 203 336 [i.5].
- Annex D (informative) provides information on TX spurious emission limit assessment below 9 kHz.
- Annex E (informative) provides information on Change history.

1 Scope

The present document specifies technical characteristics and methods of measurements for Robotic Mowers with Inductive loop systems (RMI) operating within the frequency range 100 Hz to 148,5 kHz.

The present document covers the following RMI systems:

- RMI1 systems: RMI systems without receive only mode
- RMI2 systems: RMI systems with receive only mode

NOTE 1: In RMI1 systems the robotic mower is not able to restart automatically if the boundary signal comes back after the loss of the boundary signal (safe mode, see clause 4.2.2.3), while in RMI2 systems the robotic mower is able to restart automatically after the boundary signal is back. This differentiation has been introduced to cover receiver spurious emissions for RMI2 systems.

These radio equipment types are capable of operating in all or part of the frequency bands given in table 1.

Table 1: Permitted range of operation

Permitted range of operation	
Transmit	100 Hz to 148,5 kHz
Receive	100 Hz to 148,5 kHz
NOTE:	It should be noted that the frequency range between 9 kHz and 148,5 kHz is EU wide harmonised for inductive Short Range Devices according to EC Decision 2017/1483/EU [i.2].

NOTE 2: The relationship between the present document and essential requirements of article 3.2 of Directive 2014/53/EU [i.3] is given in Annex A.

The present document only covers RMI systems with antenna sizes smaller than 1,67 km, see CEPT/ERC/REC 70-03 [i.1], Annex 9.

NOTE 3: The antenna size is described by the distance between those two points on the antenna that have the largest distance between them (e.g. for a rectangle shaped antenna the largest diagonal; for a circular shaped antenna the diameter).

2 References

2.1 Normative references

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the referenced document (including any amendments) applies.

Referenced documents which are not found to be publicly available in the expected location might be found at <https://docbox.etsi.org/Reference/>.

NOTE: While any hyperlinks included in this clause were valid at the time of publication, ETSI cannot guarantee their long term validity.

The following referenced documents are necessary for the application of the present document.

- [1] ETSI EN 300 330 (V2.1.1) (02-2017): "Short Range Devices (SRD); Radio equipment in the frequency range 9 kHz to 25 MHz and inductive loop systems in the frequency range 9 kHz to 30 MHz; Harmonised Standard covering the essential requirements of article 3.2 of Directive 2014/53/EU".

2.2 Informative references

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the referenced document (including any amendments) applies.

NOTE: While any hyperlinks included in this clause were valid at the time of publication, ETSI cannot guarantee their long term validity.

The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

- [i.1] CEPT/ERC/REC 70-03: "Relating to the use of Short Range Devices (SRD)".
- [i.2] Commission Implementing Decision (EU) 2017/1483 of 8 August 2017 amending Decision 2006/771/EC on harmonisation of the radio spectrum for use by short-range devices and repealing Decision 2006/804/EC.
- [i.3] Directive 2014/53/EU of the European Parliament and of the Council of 16 April 2014 on the harmonisation of the laws of the Member States relating to the making available on the market of radio equipment and repealing Directive 1999/5/EC.
- [i.4] CEPT/ERC/REC 74-01: "Unwanted emissions in the spurious domain".
- [i.5] ETSI EG 203 336 (V1.2.1): "Guide for the selection of technical parameters for the production of Harmonised Standards covering article 3.1(b) and article 3.2 of Directive 2014/53/EU".
- [i.6] Commission Implementing Decision C(2015) 5376 final of 4.8.2015 on a standardisation request to the European Committee for Electrotechnical Standardisation and to the European Telecommunications Standards Institute as regards radio equipment in support of Directive 2014/53/EU of the European Parliament and of the Council.
- [i.7] EG MF Robotic Mowers Boundary Wire Standard RLM003-1.1/2016.
- [i.8] EN 50636-2-107:2015: "Safety of household and similar appliances - Part 2-107: Particular requirements for robotic battery powered electrical lawnmowers", produced by CENELEC.
- [i.9] Void.
- [i.10] ETSI EN 303 454 (V1.1.1): "Short Range Devices (SRD); Metal and object detection sensors in the frequency range 1 kHz to 148,5 kHz; Harmonised Standard covering the essential requirements of article 3.2 of Directive 2014/53/EU".
- [i.11] Void.
- [i.12] Void.
- [i.13] EN 55016-1-1:2010 + A1:2010 + A2:2014: "Specification for radio disturbance and immunity measuring apparatus and methods -Part 1-1: Radio disturbance and immunity measuring apparatus - Measuring apparatus", produced by CENELEC.
- [i.14] ETSI TS 103 567 (V1.1.1): "Requirements on signal interferer handling".
- [i.15] ETSI TS 103 051 (V1.1.1) (08-2011): "Electromagnetic compatibility and Radio spectrum Matters (ERM); Expanded measurement uncertainty for the measurement of radiated electromagnetic fields".

koniec náhľadu – text d'alej pokračuje v platenej verzii STN