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| <b>STN</b> | <b>Zdokonalený systém navádzania a riadenia pohybu na prevádzkových plochách (A-SMGCS)<br/>Časť 5: Harmonizovaná norma pre prístup k rádiovému spektru pre multilateračné zariadenia (MLAT)<br/>Oddiel 1: Prijímače a budiče</b> | <b>STN<br/>EN 303 213-5-1<br/>V2.1.1</b><br><br><b>87 3213</b> |
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Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 5: Harmonised Standard for access to radio spectrum for Multilateration (MLAT) equipment; Sub-part 1: Receivers and Interrogators

Táto norma obsahuje anglickú verziu európskej normy.  
This standard includes the English version of the European Standard.

Táto norma bola oznámená vo Vestníku ÚNMS SR č. 03/24

Obsahuje: EN 303 213-5-1 V2.1.1:2023

**138149**

# ETSI EN 303 213-5-1 v2.1.1 (2023-10)



**Advanced Surface Movement Guidance and  
Control System (A-SMGCS);  
Part 5: Harmonised Standard for access to  
radio spectrum for Multilateration (MLAT) equipment;  
Sub-part 1: Receivers and Interrogators**

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Reference

REN/ERM-TGAERO-100

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Keywordsaeronautical, harmonised standard,  
interoperability, radio**ETSI**

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# Foreword

This Harmonised European Standard (EN) has been produced by ETSI Technical Committee Electromagnetic compatibility and Radio spectrum Matters (ERM).

The present document has been prepared under the Commission's standardisation request C(2015) 5376 final [i.3] to provide one voluntary means of conforming to the essential requirements of Directive 2014/53/EU on the harmonisation of the laws of the Member States relating to the making available on the market of radio equipment and repealing Directive 1999/5/EC [i.1].

Once the present document is cited in the Official Journal of the European Union under that Directive, compliance with the normative clauses of the present document given in Table A.1 confers, within the limits of the scope of the present document, a presumption of conformity with the corresponding essential requirements of that Directive, and associated EFTA regulations.

The present document is part 5, sub-part 1, of a multi-part deliverable covering Advanced Surface Movement Guidance and Control System (A-SMGCS), as identified below.

- Part 1: "Community Specification for A-SMGCS surveillance service including external interfaces";
- Part 2: "Community Specification for A-SMGCS airport safety support service";
- Part 3: "Community Specification for a deployed cooperative sensor including its interfaces";
- Part 4: "Community Specification for a deployed non-cooperative sensor including its interfaces";

**Part 5: "Harmonised Standard for access to radio spectrum for Multilateration (MLAT) equipment":****Sub-part 1: "Receivers and Interrogators";**

Sub-part 2: "Reference and vehicle transmitters";

Part 6: "Harmonised Standard for access to radio spectrum for deployed surface movement radar sensors";

Part 7: "Community Specification for A-SMGCS routing service";

Part 8: "Community Specification for A-SMGCS guidance service".

| <b>National transposition dates</b>  |                 |
|--|-----------------|
| Date of adoption of this EN:   | 3 October 2023  |
| Date of latest announcement of this EN (doa):  | 31 January 2024 |
| Date of latest publication of new National Standard or endorsement of this EN (dop/e): | 31 July 2024    |
| Date of withdrawal of any conflicting National Standard (dow):                         | 31 July 2025    |

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## Introduction

A-SMGCS are systems providing routing, guidance, surveillance and control to aircraft and affected vehicles in order to maintain movement rate under all local weather conditions within the Aerodrome Visibility Operational Level (AVOL) whilst maintaining the required level of safety.

# 1 Scope

The present document specifies technical characteristics and methods of measurements for the following equipment:

- 1) Interrogators transmitting in the 1 030 MHz band, used in Mode S multilateration equipment in an Advanced Surface Movement Guidance and Control System (A-SMGCS).
- 2) Receivers, receiving in the 1 090 MHz band, used in Mode S multilateration equipment in an Advanced Surface Movement Guidance and Control System (A-SMGCS).

Antennas for this equipment are passive without an additional amplifier.

NOTE: The relationship between the present document and essential requirements of article 3.2 of Directive 2014/53/EU [i.1] is given in Annex A.

# 2 References

## 2.1 Normative references

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The following referenced documents are necessary for the application of the present document.

- [1] [ICAO Annex 10, Volume IV](#): "Surveillance Radar and Collision Avoidance Systems", 5<sup>th</sup> edition, July 2014, including amendments up to amendment 91 dated 18-07-2022.
- [2] Void.
- [3] [ETSI EN 300 019-1-3 \(V2.4.1\) \(04-2014\)](#): "Environmental Engineering (EE); Environmental conditions and environmental tests for telecommunications equipment; Part 1-3: Classification of environmental conditions; Stationary use at weatherprotected locations".
- [4] [ETSI EN 300 019-1-4 \(V2.2.1\) \(04-2014\)](#): "Environmental Engineering (EE); Environmental conditions and environmental tests for telecommunications equipment; Part 1-4: Classification of environmental conditions; Stationary use at non-weatherprotected locations".

## 2.2 Informative references

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The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

- [i.1] [Directive 2014/53/EU](#) of the European Parliament and of the Council of 16 April 2014 on the harmonisation of the laws of the Member States relating to the making available on the market of radio equipment and repealing Directive 1999/5/EC.

- [i.2] ITU Radio Regulations (2020).
- [i.3] [Commission Implementing Decision C\(2015\) 5376 final of 4.8.2015](#) on a standardisation request to the European Committee for Electrotechnical Standardisation and to the European Telecommunications Standards Institute as regards radio equipment in support of Directive 2014/53/EU of the European Parliament and of the Council.
- [i.4] [ECC/Recommendation \(02\)05 \(2012\)](#): "Unwanted emissions".
- [i.5] ETSI EG 203 336 (V1.2.1): "Guide for the selection of technical parameters for the production of Harmonised Standards covering article 3.1(b) and article 3.2 of Directive 2014/53/EU".
- [i.6] [ERC/Recommendation 74-01 \(2019\)](#): "Unwanted emissions in the spurious domain".
- [i.7] EUROCAE ED-117A (September 2016): "MOPS for Mode S Multilateration Systems for Use in Advanced Surface Movement Guidance and Control Systems (A-SMGCS)".

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